The keypad indication would display "LOC.".

When F = 2/7, the Forward or Reverse function is displayed.

NOTE:

If a forward or reverse button on the keypad is pressed and released, the display will return to the previous setting.

![Diagram](image)

- F = 0: Operation mode selection
  - F0: Operation mode selection
  - F1: Run / Forward / Reverse
  - F2: Stop / Forward / Reverse

![Diagram](image)

- F = 0: Operation mode selection = 0: Forward
  - Forward
  - Reverse
  - NO
  - YES

![Diagram](image)

- F = 7: Operation mode selection
  - F7: External operation control
  - F8: External operation control

![Diagram](image)

- F = 0: Pattern setting = 0 - 6
  - P05 = 1
  - P06 = 1
  - P07 = 1
  - P08 = 1

![Diagram](image)
F.13: Torque-compensation gain 0 - 10 %

Connect the output of the process to the input of the controller. Apply the torque compensation gain to the output signal of the controller. The compensated output is then applied to the drive as the reference torque signal.

NOTE: The output of the controller is limited to 100% of its maximum output.

F.10: Standby/Stop control

The standby/stop control is used to stop the drive or to set it to standby mode. To stop the drive, press the stop button. To set the drive to standby mode, press the standby button.

NOTE: The drive will not start again unless the start button is pressed after being in standby mode.

F.0: Frequent output range

The frequent output range is set according to the application requirements. For example, in a conveyor system, a higher output range may be required to accommodate the varying load conditions.

NOTE: The output range is limited to 100% of the maximum output of the drive.

F.00: Frequency references

The frequency references are used to set the desired frequency output of the drive. These references can be set using the frequency reference input or through the communication interface.

NOTE: The frequency references are limited to 100% of the maximum output of the drive.